

## Bayesian Updating

Consider first the case of coin tosses.

- you are trying to estimate  $p$ , the probability of heads
- you need a prior density for  $p$ , call it  $\pi(p)$
- your data is  $k$ , the number of heads in  $n$  tosses
- you want the posterior density for  $p$ ,  $\pi(p|k)$

If you choose your prior to be a  $\text{Beta}(\alpha, \beta)$  distribution:

$$\pi(p) = \frac{(\alpha + \beta - 1)!}{(\alpha - 1)! (\beta - 1)!} p^{\alpha-1} (1 - p)^{\beta-1}$$

then your posterior has a  $\text{Beta}(\alpha + k, \beta + n - k)$  distribution.

Updating is simple: you add the number of heads  $k$  to  $\alpha$ , and the number of tails  $n - k$  to  $\beta$ .

This gives you a density on  $[0,1]$ , which describes your opinion of  $p$  after seeing the data.

If you want a single estimate for  $p$ , it makes sense to take the value where the density is highest, which happens to be

$$\frac{\alpha + k - 1}{\alpha + \beta + n - 2}$$

If you take various starting values for  $\alpha$  and  $\beta$ , this gives you various estimates. If your prior is reasonable, the estimates are reasonable. In some cases, they may be better than the “obvious” estimator  $k/n$ .

The posterior probability that  $p$  falls in a certain interval is just the relevant area under the density curve. Hence you can get confidence intervals for  $p$ .

## Bayesian Updating: The General Case

- you want to estimate some parameter  $\theta$
- first you need a prior  $\pi(\theta)$
- then you observe the data  $X$ ; you need to know its distribution conditional on  $\theta$ ,  $f(x|\theta)$
- then the posterior is  $\pi(\theta|x) = C \cdot \pi(\theta) \cdot f(x|\theta)$  where the constant  $C$  depends on  $x$  (not on  $\theta$ ) and is chosen so that the posterior integrates to 1

The hard part is usually computing  $C = 1 / \int \pi(\theta) \cdot f(x|\theta)d\theta$ :

- sometimes you can choose your prior in such a way that  $C$  can be computed explicitly (e.g. beta distribution for Bernoulli trials)
- with a computer, you can try to do the integral by brute force
- a smarter way is a technique called MCMC (Markov chain Monte Carlo) that computes the posterior indirectly as a byproduct of running a Markov chain. This is a fashionable approach.