

uncorrelated so that Θ is diagonal, the covariance matrix of (y_{11}, y_{22}) is

$$\Sigma = \begin{pmatrix} \phi_{11} + \theta_{11} & \lambda_1^2 \phi_{11} + \theta_{22} & \lambda_1 \phi_{21} & \lambda_1 \phi_{21} \\ \lambda_1 \phi_{11} & \lambda_1 \phi_{21} & \lambda_1 \lambda_2 \phi_{21} & \lambda_1 \phi_{21} \\ \lambda_2 \phi_{21} & \lambda_2 \phi_{22} & \lambda_2 \phi_{22} & \lambda_2^2 \phi_{22} + \theta_{44} \end{pmatrix}$$

Σ has 10 variances and covariances that are functions of nine parameters. The model has one degree of freedom.

Often when the same variables are used repeatedly, there is a test for the corresponding errors (the ϵ 's) to correlate over time (see previous sections on autoregressive models) because of memory and other effects. Hence, there is a need to generalize the preceding model to correlations between ϵ_{11} and ϵ_{21} and also between ϵ_{12} and ϵ_{22} . This means that there will be two nonzero covariances θ_{31} and θ_{42} in Θ . The covariance matrix is shown in Figure 11.5. The covariance matrix of the observed variables will now be

$$\Sigma = \begin{pmatrix} \phi_{11} + \theta_{11} & \lambda_1^2 \phi_{11} + \theta_{22} & \lambda_1 \phi_{21} & \lambda_1 \phi_{21} \\ \lambda_1 \phi_{11} & \lambda_1 \phi_{21} & \lambda_1 \lambda_2 \phi_{21} & \lambda_1 \phi_{21} \\ \lambda_2 \phi_{21} & \lambda_2 \phi_{22} & \lambda_2 \phi_{22} & \lambda_2^2 \phi_{22} + \theta_{44} \\ \lambda_1 \phi_{21} & \lambda_1 \lambda_2 \phi_{21} & \lambda_2 \phi_{22} + \theta_{33} & \lambda_2 \phi_{22} + \theta_{44} \end{pmatrix}$$

This Σ has its 10 independent elements expressed in terms of 11 parameters. Hence, it is clear that the model is not identified. In fact, none of the parameters are identified without further restrictions. The loading λ_2 may be multiplied by a constant and the ϕ 's divided by the same constant. This does not change σ_{21} , σ_{32} , σ_{41} , and σ_{43} . The change in the other model identified one must fix one λ or one ϕ at a nonzero value or at some arbitrary value. However, the correlation between η_1 and η_2 is identified without any restrictions, since

$$\text{Corr}(\eta_1, \eta_2) = [\phi_{21}^2 / (\phi_{11} \phi_{22})]^{1/2} = [(\sigma_{32} \sigma_{41}) / (\sigma_{21} \sigma_{43})]^{1/2}$$

This model may therefore be used to estimate this correlation coefficient and to test whether this is 1. The maximum-likelihood estimate of the correlation coefficient is $[(s_{32}s_{41}) / (s_{21}s_{43})]^{1/2}$. To make further use of the model it is necessary to make some assumption about the nature of the variables. For example, if it can be assumed that the two variables at occasion are τ -equivalent (see, e.g., Lord & Novick, 1968) we can set λ_1 and λ_2 equal to 1. Then the model can be estimated and tested with one degree of freedom.

Structural Equation Models

Joreskog

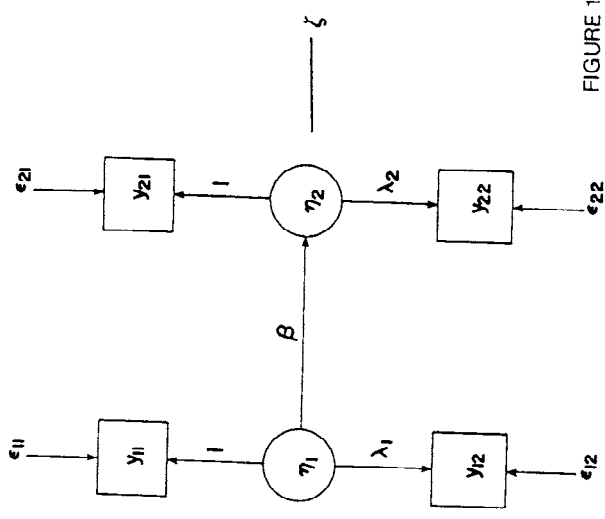


FIGURE 11.4. A two-wave-two-variable model.

equation $\eta_2 = \beta\eta_1 + \zeta$, (28)

the regression of η_2 on η_1 . In particular, we are interested in whether $\beta = 1$ and ζ is small; that is, whether the same latent variables are measured on both occasions.

The measurement-model part of the model may be written as

$$\begin{pmatrix} y_{11} \\ y_{12} \\ y_{21} \\ y_{22} \end{pmatrix} = \begin{bmatrix} 1 & 0 \\ \lambda_1 & 0 \\ 0 & 1 \\ 0 & \lambda_2 \end{bmatrix} \begin{pmatrix} \eta_1 \\ \eta_2 \end{pmatrix} + \begin{pmatrix} \epsilon_{11} \\ \epsilon_{12} \\ \epsilon_{21} \\ \epsilon_{22} \end{pmatrix}, \quad (29)$$

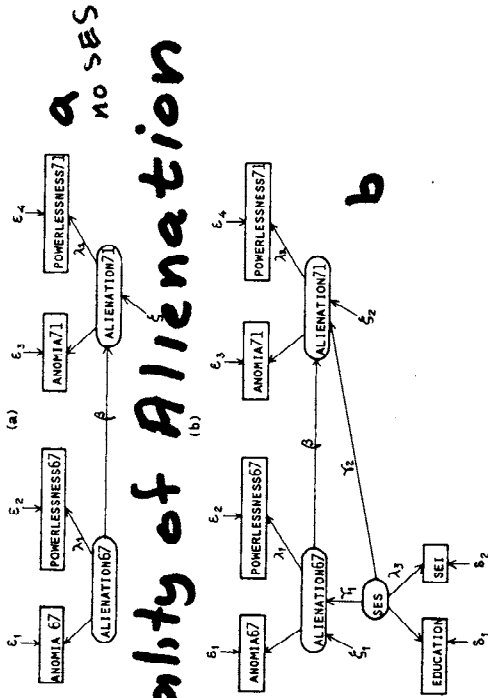
where it is assumed that η_1 and η_2 are measured in the same metric as y_{11} and y_{21} , respectively. This model is a special case of the general LISREL model with no x . In terms of LISREL, Eq. (28) may be interpreted, in accordance with Eq. (4), as

$$\begin{pmatrix} 1 & 0 \\ -\beta & 1 \end{pmatrix} \begin{pmatrix} \eta_1 \\ \eta_2 \end{pmatrix} = \begin{pmatrix} \zeta_1 \\ \zeta_2 \end{pmatrix},$$

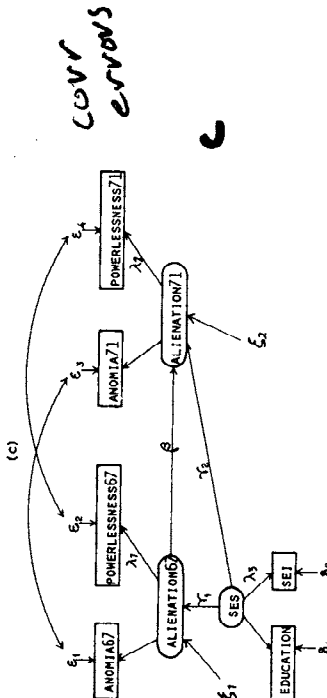
regression for latents

where $\zeta_1 = \eta_1$ and $\zeta_2 = \zeta$. Let Φ be the covariance matrix of (η_1, η_2) and let Θ be the covariance matrix of $(\epsilon_{11}, \epsilon_{12}, \epsilon_{21}, \epsilon_{22})$. If all the ϵ 's are

Stability of Alienation



a NO SES



c CORR errors

FIGURE 6. Models for study of stability of alienation.

TABLE 1

Parameter	Model 6a	Model 6b	Model 6c
λ_1	0.815 (0.040)	0.888 (0.041)	0.979 (0.062)
λ_2	0.847 (0.042)	0.849 (0.040)	0.922 (0.059)
λ_3		5.331 (0.430)	5.221 (0.422)
β	0.789 (0.044)	0.705 (0.054)	0.607 (0.051)
γ_1		-0.614 (0.056)	-0.575 (0.056)
γ_2		-0.174 (0.054)	-0.227 (0.052)
ψ_{11}		5.307 (0.473)	4.847 (0.468)
ψ_{22}		3.742 (0.388)	4.089 (0.405)
ϕ		6.663 (0.641)	6.803 (0.650)
σ_{η_1}		1.717 (0.145)	1.675 (0.151)
σ_{η_2}		16.153 (0.365)	16.273 (0.358)
σ_{η_3}	1.906 (0.097)	2.004 (0.086)	2.176 (0.104)
σ_{η_4}	1.865 (0.077)	1.786 (0.076)	1.602 (0.126)
σ_{η_5}	1.827 (0.109)	1.923 (0.097)	2.098 (0.123)
σ_{η_6}	1.969 (0.077)	1.904 (0.077)	1.754 (0.124)
$\text{CORT}(\epsilon_1, \epsilon_2)$			0.356 (0.047)
$\text{CORT}(\epsilon_3, \epsilon_4)$			0.121 (0.082)
χ^2	61.155	71.544	4.770
d.f.	1	6	4

Parameter estimates for the models in Figure 6a-c (standard errors in parentheses).

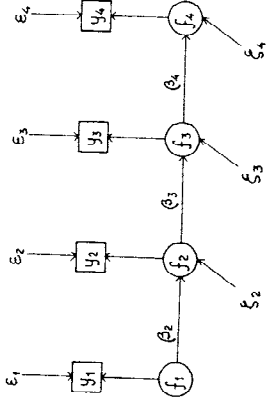


FIGURE 7. A simplex model.

The simplex model can be put into the LISREL format, with no x . We write

$$\begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \end{bmatrix} + \begin{pmatrix} 0 \\ \epsilon_2 \\ \epsilon_3 \\ 0 \end{pmatrix} \quad (41)$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ -\beta_2 & 1 & 0 & 0 \\ 0 & -\beta_3 & 1 & 0 \\ 0 & 0 & -\beta_4 & 1 \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \end{bmatrix} = \begin{bmatrix} \zeta_1 \\ \zeta_2 \\ \zeta_3 \\ \zeta_4 \end{bmatrix} \quad (42)$$

covariance matrix of y_1, y_2, y_3 and y_4 is

$$\Sigma = \begin{bmatrix} \phi_1 + \theta_1^2 & & & \\ \beta_2 \phi_1 & \phi_2 + \theta_2^2 & & \\ \beta_3 \beta_2 \phi_1 & \beta_3 \phi_2 & \phi_3 + \theta_3^2 & \\ \beta_4 \beta_3 \beta_2 \phi_1 & \beta_4 \beta_2 \phi_2 & \beta_4 \phi_3 & \phi_4 + \theta_4^2 \end{bmatrix} \quad (40)$$

c.f. Satisfying a simplex structure is simpler than it should be